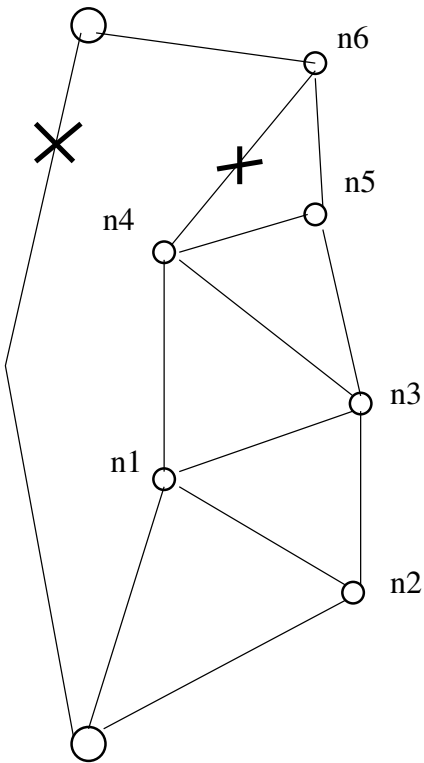


Goal

Optimal  
route



Start